

Features

- Direct drive servo motor
- +/- 60 degrees travel
- 38m tall
- 110mm center aperture
- 0.43 arc-sec resolution
- Single electrical cable connection
- Class 10 option

Overview

The Primatics PLR110 rotary stage is an advanced, direct drive rotary axis. It features large center aperture and a high resolution rotary encoder. High repeatability and fast settle times making the PLR110 ideal for semiconductor wafer inspection, high speed laser machining and precision metrology. The compact design also yields a smaller footprint than comparable worm drives.

Applications

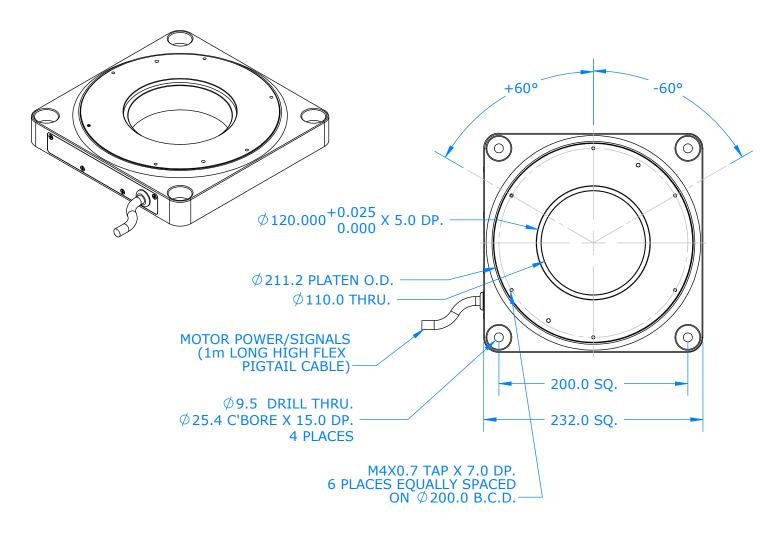
The PLR110 has a high pole count motor which aids in obtaining low velocity ripple. The PLR110's high performance motor coupled with its high resolution optical encoder results in high servo stiffness over a wide dynamic range.

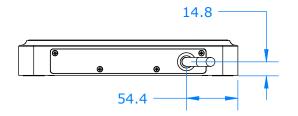
Features

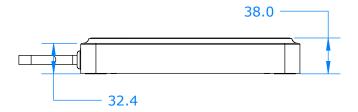
Standard features include forward and reverse limit sensors and a protective hard cover. The large 110mm diameter center aperture facilitates top and bottom side access to an attached payload.



Dimensions







Specifications

Specification	Notes	PLR110
Travel (degrees)		+/- 60
Resolution (arc-sec)	2	0.43
Accuracy (arc-sec)	1, 2	+/- 30
Bi-directional Repeatability (arc-sec)	1	+/- 2
Axial Runout (µm)	1	+/- 3
Radial Runout (µm)	1	+/- 5
Axial Load Capacity (kg)		2.0
Radial Load Capacity (kg)		0.8
Maximum Speed (deg/sec)		45
Platen Inertia (kg-m^2)		0.0066
Stage Weight (kg)		3.8

Notes: 1 - Stage affixed to flat continuous surface, 2 - Slope Corrected. All specifications subject to change without notice.

Motor / Encoder, Limit Data

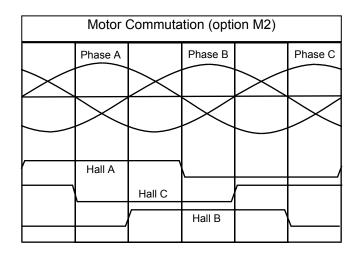
Parameter	Notes	Value
Motor		
Motor Type		Brushless Servo
Continuous Torque (N-m)	1	0.5
Continuous Current (Arms)	1	1.52
Peak Torque (N-m)	2	1.8
Peak Current (Arms)	2	5.45
Torque Constant (N-m/Arms)		0.33
Back EMF Constant (V/Krpm)		28.5
Winding Resistance (ohms)		3.7
Winding Inductance (mH +/- 25%)		3.5
Thermal Resistance (C/W)		1.2
Poles		36
Hall Sensor Power		5 to 24VDC, 50mA
Hall Outputs		Open collector, current sinking, 20mA max
Encoder		
Encoder power		5VDC +/- 5%, 150mA
Output		Square wave differential line driver
Index		Synchronized pulse, duration equal to one resolution bit
Limit Sensors		
Limit Power		12 to 24VDC, 50mA
Output - L1 and L2 options		Current sinking, 50mA max

Notes: 1 - At 15°C temperature rise; 2 - At 10% duty cycle and 1 second maximum. All specifications subject to change without notice.

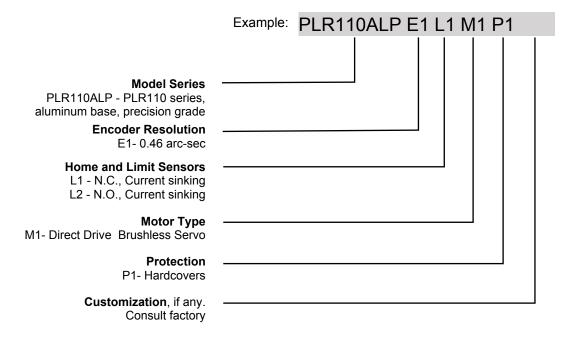


Connectors

	Servo Motor (option M2)			
Connector: Cannon 192926-0480 Size 20, 28 pins				
Pin	Function			
Α	Motor Phase A			
В	Motor Phase B			
С	Motor Phase C			
D	Motor Shield			
E	Encoder 5V			
F	Encoder Ch A+			
G	Encoder Ch A-			
Н	Encoder Ch B+			
J	Encoder Ch B-			
K	Encoder Shield			
L	Limit Power			
М	Limit Return and Signal Common			
N	Home Sensor			
Р	Not Used			
R	Not USed			
S	Signal Shield			
Т	Hall V+			
U	Hall V-			
V	Encoder Power Return			
W	Encoder Ch I+			
Х	Encoder Ch I-			
Y	Forward Limit - Activates at Full Forward Travel			
Z	Reverse Limit - Activates at Full Reverse Travel			
а	KEY			
b	Hall A			
С	Hall B			
d	Temp Sensor			
е	Hall C			



Model Configuration



Not all configurations are valid - consult factory for assistance

Accessories

Model	Description
CABLE-SENSORS-PIGTAIL	Cable assembly for Limit connector. Un-terminated at user end. 12 ft standard.
CABLE-SERVO-STAGE-PIG- TAIL	Cable assembly for M2 option. Un-terminated at user end. 12 ft standard
CABLE-SERVO-STAGE- DMC40X0-I200	Cable assembly for M2 option for use with Galil DMC-40x0-I200 with trap servo drives. 12 ft standard.
CABLE-SERVO-STAGE- DMC40X0-I200-SINE	Cable assembly for M2 option for use with Galil DMC-40x0-I200 with sine servo drives. 12 ft standard.
CABLE SERVO STAGE MC4U W/ HALLS	Cable assembly for M2 option for use with ACS MC4U. 12 ft standard.
CABLE-SERVO-ACS-CMNT- DIG	Cable assembly for M2 option for use with ACS MC4U. 12 ft standard.

