## CE KIR REACH

# MDrive<sup>®</sup>Plus MDI•34 programmable Motion Control

## **Product overview**

MDrive<sup>®</sup> Plus Motion Control products integrate 1.8° 2-phase stepper motor, fully programmable motion controller, drive electronics and optional encoder. Products with encoders include stall detection, position maintenance, and find index mark.

Programming for these stand-alone motion control solutions is via RS-422/485 interface with MCode software using simple 1 to 2 character instructions.

### Application areas

MDrive Plus products deliver reliable performance for new and existing motion control applications. Satisfying the requirements for a wide range of machine builders.

Simplify your machine design and reduce cabinet size by replacing multiple components with a single compact integrated motor. Fewer individual system components eliminates multiple potential failure points, and lowers risk of electrical noise by eliminating cabling between motor and drive.

These compact, powerful and cost effective motion control solutions deliver exceptional smoothness and performance that can reduce system cost, design and assembly time for a large range of 2-phase stepper motor applications.



MDI-34 MDrive Plus programmable Motion Control products: integrated NEMA34 motor and controls, IP20-rated

#### General features

Compact integrated microstepping drive, prog	grammable motion controller and NEMA34 1.8° 2-phase stepper motor
Advanced current control for exceptional perf	ormance and smoothness
+12 to +75 VDC single supply	
20 microstep resolutions up to 51,200 steps p	er rev including: Degrees, Metric, Arc Minutes
Auxiliary logic power supply input	
0 to 5 MHz step clock rate selectable in 0.59	Hz increments
Up to 8 I/O lines	
One 10 bit selectable analog input	
Communication	RS-422/485
Protection	IP20 rating
	Thermal temp warning, over voltage/current
Programmable	Motor run/hold current
Available options	Motor stack lengths
	Connector options
	Encoders
	Rear control knob for manual positioning
Graphical user interface provided for quick an	d easy parameter setup



# MDI•34 programmable Motion Control

## **Specifications**

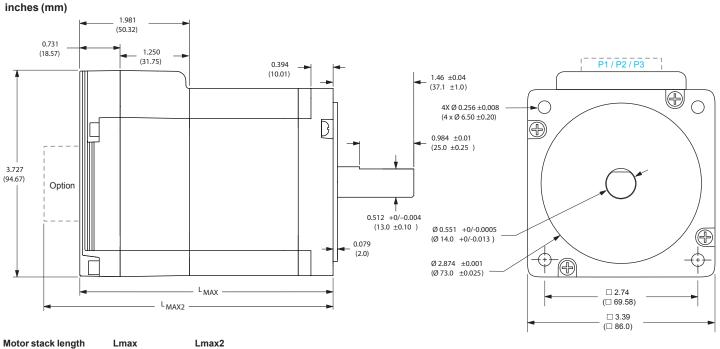
Communication	Protocol type	RS-422/485	4.8 to 115.2 kbps baud rate		
Input power	Voltage	VDC	+12+75		
	Current maximum (1)	Amp	4.0		
Vlotor	Frame size	NEMA	34		
		inches	3.4		
		mm	85		
	Holding torque	oz-in	4081090		
		N-cm	288 770		
	Length	stack sizes	1, 2 & 3		
Thermal	Operating temp	Heat sink maximum	75°C		
	non-condensing	Motor maximum	90°C		
Protection	Туре	IP rating	IP20		
		Temp warning	Thermal, over voltage/current		
		I/O warnings	Over temp, short circuit, transient, over voltage, inductive clamp		
Auxiliary logic input	Voltage range		+12 to +24 VDC When input voltage is removed, maintains power onl to control and feedback circuits.		
Analog input	Resolution		10 bit		
0	Voltage range		0 to +5 VDC, 0 to +10 VDC, 0-20 mA, 4-20 mA		
General purpose I/O	N-cm         288 770           Length         stack sizes         1, 2 & 3           Operating temp         Heat sink maximum         75°C           non-condensing         Motor maximum         90°C           Type         IP rating         IP 20           Temp warning         Thermal, over voltage/current         I/O warnings           Voltage range         Voltage range         10 bit           Voltage range         0 to +5 VDC, 0 to +10 VDC, 0-20 mA, 4-20 mA           Output sinking current         Up to 600 mA           Plus products         Number         4           Type         Inputs and outputs tolerant to +24 VDC vingo is rinking outputs           Plus? products         Number         4           Plus? products         Number         8 or 4 (2)           Type         Sourcing or sinking outputs inputs, or sinking outputs tole compatible           Open loop configuration         Number of settings         20           Steps per revolution         200,400,800,1000,1600,2000,3200,5000,6400,10000,1280           Counters         Type         Sourcing outputs +12 to +24 VDC, inputs and sinking outputs tole to +24 VDC, inputs and sinking outputs +12 to +24 VDC, inputs and sinking outputs tole to +2				
		Number			
	·		Sourcing or sinking inputs, or sinking outputs		
	Plus <sup>2</sup> products	<u> </u>			
	····				
			Sourcing outputs +12 to +24 VDC, inputs and sinking outputs tolerant		
Notion	Open loop configura-	Number of settings			
			200, 400, 800, 1000, 1600, 2000, 3200, 5000, 6400, 10000, 12800, 20000, 25000, 25600, 40000, 50000, 51200, 36000 (0.01 deg/µstep).		
	Counters	Type			
	Counters				
	Velocity	· · · · · · · · · · · · · · · · · · ·			
	velocity				
	Accel/Decel				
	///////////////////////////////////////				
	Position foodback				
Expanded motion					
Plus <sup>2</sup> products only					
nuo produoto onny					
	High speed I/O				
	riigii speed i/O	F Usition capture			
		Trip output			
		mp output			
	Position feedback	Optional	Remote encoder interface required		
Software	Program storage	Type/size	Flash/6384 bytes		
Soliware		Type/Size	Four 32 bit		
	User registers	veriables			
	User program labels &	variables			
	Math functions		+, x, ÷, >, <, <=, >=, AND, OR, XOR, NOT		
	Branch functions	Innuta	Branch and Call		
	General purpose I/O functions	Inputs	home, limit plus, limit minus, go, stop, pause, jog plus, jog minus, general purpose		
		Outputs	moving, fault, stall, velocity change, general purpose		
	Trip functions		Trip on input, trip on position, trip on time, trip capture, trip on relative position		
	Party mode addresses		62		
	Encoder functions		Stall detection, position maintenance, find index		

(1) Actual power supply current will depend on voltage and load.
(2) I/O is reduced from 8 to 4 for products with remote encoder option.
(3) Adjusting the microstep resolution can increase the range.

# MDI•34 programmable Motion Control

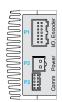
## Dimensions

## MDI-34 NEMA34 motor, IP20-rated



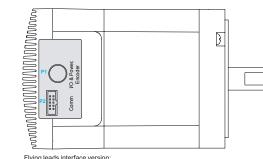
MOLOF SLACK length	Lillax	
Single	3.81 (96.77)	4.52 (114.81)
Double	4.60 (116.84)	5.31 (134.87)
Triple	6.17 (156.72)	6.88 (174.75)

#### Connector options



Pluggable interface version: 14-pin\* and 2-pin locking wire crimp and 10-pin friction lock wire crimp connectors

\* 14-pin replaced by 20-pin locking wire crimp connector when optional remote encoder is included



Flying leads interface version: 12" (305mm) flying leads with 10-pin non-locking IDC connector

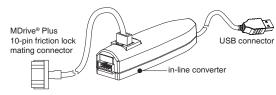
#### Lmax2 option



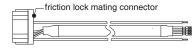
# MDI•34 programmable Motion Control



MD-CC400-001



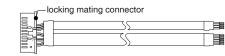
MD-CC402-001



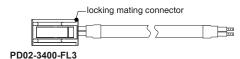
#### PD10-1434-FL3



### PD14-2334-FL3



#### PD20-3400-FL3



#### Accessories

description	length feet (m)	part number
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#### QuickStart Kit

For rapid design verification, all-inclusive QuickStart Kits includes prototype development cables and a communication converter for MDrive Plus initial functional setup and system testing.		
For all MDrive34 programmable Motion Control products	_	add "K" to part number

#### Communication converter

Electrically isolated, in-line converter pre-wired with mating connector to conveniently set/program communication parameters for a single MDrive Plus via a PC's USB port.

Mates to 10-pin non-locking IDC connector	12.0 (3.6)	MD-CC400-001
Mates to 10-pin friction lock wire crimp connector	12.0 (3.6)	MD-CC402-001

## Prototype development cable

Speed test/development with pre-wired mating connector with other cable end open.

Mates to 10-pin locking wire crimp connector for I/O and remote encoder option	10.0 (3.0)	PD10-1434-FL3
Mates to 14-pin locking wire crimp connector for I/O and remote encoder option	10.0 (3.0)	PD14-2334-FL3
Mates to 20-pin locking wire crimp connector for I/O and remote encoder option	10.0 (3.0)	PD20-3400-FL3
Mates to 2-pin locking wire crimp connector for power	10.0 (3.0)	PD02-3400-FL3

#### Mating connector kits

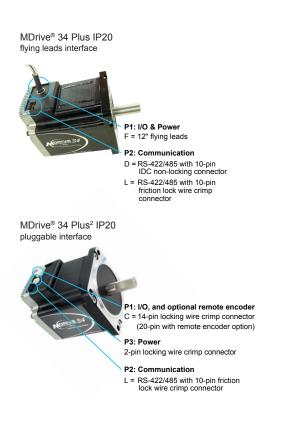
Connectors for assembly of cables, cable material not supplied. Sold in lots of 5. Manufacturer's crimp tool recommended for crimp connectors.

10-pin friction lock wire crimp connector for com- munication	—	СК-02
14-pin locking wire crimp connector for I/O and remote encoder option	—	СК-09
20-pin locking wire crimp connector for I/O and remote encoder option	—	СК-11
2-pin locking wire crimp connector for power	_	CK-05
10-pin non-locking IDC connector for communication	_	CK-01

#### Drive protection module

Limits surge current and voltage to a safe level when DC input power is switched on-and-off to an MDrive Plus. For all MDrive34 programmable Motion Control — DPM75 products

# MDI•34 programmable Motion Control



### Part numbers

### IP20-rated products

example part number	κ	М	D	I	1	F	R	D	3	4	A	7	-N
QuickStart Kit K = kit option, omit from part number if unwanted	К	Μ	D	I	1	F	R	D	3	4	A	7	-N
MDrivePlus version MDI = Intelligent — programmable Motion Control	K	M	D	I	1	F	R	D	3	4	A	7	-N
Input 1 = Plus version with standard features 3 = Plus <sup>2</sup> version with expanded features	K	Μ	D	I	1	F	R	D	3	4	A	7	-N
P1 connector F = flying leads (1) C = wire crimp (2)	K	M	D	I	1	F	R	D	3	4	A	7	-N
Communication type R = RS-422/485	K	Μ	D	I	1	F	R	D	3	4	A	7	-N
P2 connector D = IDC (1) L = wire crimp	K	M	D	I	1	F	R	D	3	4	A	7	-N
Motor size 34 = NEMA 34 3.4" / 85mm	K	M	D	I	1	F	R	D	3	4	A	7	-N
Motor length A = single stack B = double stack C = triple stack	K	М	D	I	1	F	R	D	3	4	A	7	-N
Drive voltage 7 = +12 to +75 VDC	К	Μ	D	I	1	F	R	D	3	4	A	7	-N
Options — omit from part number if unwanted -N = rear control knob for manual positioning -EQ = internal 512-line optical encoder w/ index n -EE (2) = remote differential encoder interface; encod			ะรเ	ıpı	olie	d							-N

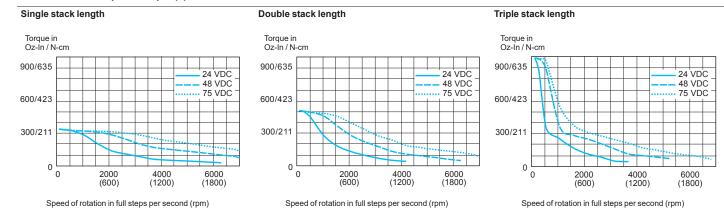
Only available with Plus products.
 Only available with Plus<sup>2</sup> products.

# MDI•34 programmable Motion Control

### Motor performance

MD•34 NEMA 34 motor specifications	Motor	Stack length	Single	Double	Triple
		oz-in	408	574	1090
	Holding torque	N-cm	288	405	770
	Detertion	oz-in	10.9	14.16	19.83
	Detent torque	N-cm	7.7	10.0	14.0
		oz-in-sec <sup>2</sup>	0.01275	0.01924	0.03849
	Rotor inertia	kg-cm <sup>2</sup>	0.90	1.35	2.70
		lb	4.1	5.5	8.8
	Weight (motor+driver)	kg	1.9	2.5	4.0

### MD•34 NEMA 34 speed torque (1)



(1) Test conditions: 100% current with damper simulating load.

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